Finite Elements in Structural Analysis

Introduction Truss and beam structures Plate and shell structures Modeling

Properties of finite elements

Compulsory requirements of finite elements

- a) Rigid body displacements must not provoke nodal forces
- Elements must be able to represent constant strains and constant stresses exactly

Optional requirements of finite elements

- c) Continuity of the displacements
- d) Geometric isotropy
- e) Rotational invariance

Properties of finite elements

Stress-free rigid body translation and rotation of an element

Example 1: Rigid body displacement of plane stress elements in analysis of cantilever.

Example 2: Rigid body displacement states at a plane stress element









Displacement in x-direction

Displacement in y-direction

Rotation on the z-axis

Properties of finite elements

Stress-free rigid body translation and rotation of an element

Example It has to be shown that for a rigid body displacement in the x-direction of the rectangular plane stress element with bilinear shape functions no nodal forces occur.

Displacement state: **u**₁

$$_{1} = \mathbf{U}_{2} = \mathbf{U}_{3} = \mathbf{U}_{4}$$

 $v_1 = 1$ $v_1 = v_2 = v_3 = v_4 = 0$

$$\begin{bmatrix} F_{1} \\ F_{2} \\ F_{3} \\ F_{4} \\ F_{5} \\ F_{6} \\ F_{7} \\ F_{8} \end{bmatrix} = \underbrace{E \cdot t}_{B_{1}} \begin{bmatrix} k_{11} & k_{12} & k_{13} & k_{14} & k_{15} & k_{16} & k_{17} & k_{18} \\ k_{21} & k_{22} & k_{23} & k_{24} & k_{25} & k_{26} & k_{27} & k_{28} \\ k_{31} & k_{32} & k_{33} & k_{34} & k_{35} & k_{36} & k_{37} & k_{38} \\ k_{41} & k_{42} & k_{43} & k_{44} & k_{45} & k_{46} & k_{47} & k_{48} \\ k_{51} & k_{52} & k_{53} & k_{54} & k_{55} & k_{56} & k_{57} & k_{58} \\ k_{61} & k_{62} & k_{63} & k_{64} & k_{65} & k_{66} & k_{67} & k_{68} \\ k_{71} & k_{72} & k_{73} & k_{74} & k_{75} & k_{76} & k_{77} & k_{78} \\ k_{81} & k_{82} & k_{83} & k_{84} & k_{85} & k_{86} & k_{87} & k_{88} \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \\ 1 \\ 0 \end{bmatrix} = \underbrace{E \cdot t}_{A_{11}} + k_{13} + k_{15} + k_{17} \\ k_{21} + k_{23} + k_{25} + k_{27} \\ k_{31} + k_{33} + k_{35} + k_{37} \\ k_{41} + k_{43} + k_{45} + k_{47} \\ k_{51} + k_{53} + k_{55} + k_{57} \\ k_{61} + k_{63} + k_{65} + k_{67} \\ k_{71} + k_{73} + k_{75} + k_{77} \\ k_{81} + k_{83} + k_{85} + k_{87} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

Stiffness matrix

Properties of finite elements

States of constant strain and constant stress

Constant strain states for a plane stress element



Constant stress states for a plane stress element





In the patch test it is checked if the "patch" of elements is able to represent constant stress states.

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Properties of finite elements

Geometric isotropy

All elements used in practice in programs are geometrically isotropic

Rotational invariance

Requires that polynomial terms are complete



Element types

- Elements with continuous displacement shape functions
 - Triangular element
 - Isoparametric elements
- Non-conforming elements
- Hybrid elements

Displacement-based finite elements

Derivation of the element stiffness matrix for elements with displacement shape functions:

- a) Determination of the shape functions of the displacements; the unknowns of the displacement functions are the nodal point displacements u_e . (The order of the displacement function must be high enough so that all derivations needed for the calculation of the strains are not equal to zero.)
- b) Determination of the strains corresponding to the displacement functions

$\underline{\varepsilon} = \underline{B} \cdot \underline{u}_{e}$

c) Formulation of the material law

$\underline{\sigma} = \underline{D} \cdot \underline{\epsilon}$

d) The nodal forces corresponding to the chosen shape functions are obtained with the principal of virtual displacements as

 $\underline{K}_{e} \cdot \underline{u}_{e} = \underline{F}_{e}$ where the element stiffness matrix is

$$\underline{\mathsf{K}}_{e} = \int \mathbf{t} \cdot \underline{\mathsf{B}}^{\mathsf{T}} \cdot \underline{\mathsf{D}} \cdot \underline{\mathsf{B}} \, dx \, dy$$

e) Determination of the nodal loads \underline{F}_{L} equivalent to the element loads

Elements with constant displacement assumptions

Single triangular element – CST- Element (Constant Strain Triangle)



Linear displacements: $\mathbf{u}(\mathbf{x},\mathbf{y}) = \alpha_1 + \alpha_2 \cdot \mathbf{x} + \alpha_3 \cdot \mathbf{y}$ $\mathbf{v}(\mathbf{x},\mathbf{y}) = \beta_1 + \beta_2 \cdot \mathbf{x} + \beta_3 \cdot \mathbf{y}$



Strains $(\epsilon_x, \epsilon_y, \epsilon_{xy})$: constant

Stresses ($\sigma_{x_1} \sigma_{y_2} \sigma_{xy}$): constant in the element

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01/23

10

3 Plate and shell structures / 3.3 Plates in plane stress

Finite elements for plane stress elements

Elements with constant displacement assumptions Isoparametric elements

polynomial order for description of the geometry = polynomial order of the shape functions.

Element types:



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Finite elements for plane stress elements

Elements with constant displacement assumptions Isoparametric elements

Isoparametric element with local curved coordinates r, s



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Isoparametric elements

Shape functions	i = 5*	i = 6*	i = 7*	i = 8*	i = 9*
$h_1 = 1/4(1 + r)(1 + s)$	-1/2 h ₅	-	-	-1/2 h ₈	-1/4 h ₉
$h_2 = 1/4(1 - r)(1 + s)$	-1/2 h ₅	-1/2 h ₆	-	-	-1/4 h ₉
$h_3 = 1/4(1 - r)(1 - s)$	-	-1/2 h ₆	-1/2 h ₇	-	-1/4 h ₉
$h_4 = 1/4(1 + r)(1 - s)$	-	-	-1/2 h ₇	-1/2 h ₈	-1/4 h ₉
$h_5 = 1/2(1 - r^2)(1 + s)$	-	-	-	-	-1/2 h ₉
$h_6 = 1/2(1 - s^2)(1 - r)$	-	-	-	-	-1/2 h ₉
$h_7 = 1/2(1 - r^2)(1 - s)$	-	-	-	-	-1/2 h ₉
$h_8 = 1/2(1 - s^2)(1 + r)$	-	-	-	-	-1/2 h ₉
$h_9 = (1 - r^2)(1 - s^2)$	-	-	-	-	-

* if nodal point i is existing

Isoparametric elements

Displacements



 $u = h_1(r,s) \cdot u_1 + h_2(r,s) \cdot u_2 + h_3(r,s) \cdot u_3 + h_4(r,s) \cdot u_4$

Strains	$\underline{\varepsilon} = \underline{B} \cdot \underline{U}$
Stresses	$\underline{\sigma} = \underline{D} \cdot \underline{\varepsilon}$
Stiffness matrix	$\underline{\mathbf{K}} = \int \underline{\mathbf{B}}^{T} \cdot \underline{\mathbf{D}} \cdot \underline{\mathbf{B}} \mathrm{dV}$

(Numerical integration according to Gauss)

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Gaussian numerical integration



Gaussian numerical integration



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Integration order n	Formula $\int_{x_a}^{x_a + \Delta x} f(x) dx = \sum_i f(x_i) \cdot \alpha_i \frac{\Delta x}{2}$	Location of integration points $r = r_j$ and $s = s_k$ in plane finite elements
3-point integration $f(x)$ $f(x)$ $f(x)$ $f(x_1)$ $f(x_2)$ $f(x_3)$ $f(x_3)$ $f(x_1)$ $f(x_2)$ $f(x_3)$ $f(x_$	$\int_{x_a}^{x_a + \Delta x} f(x) dx = (\alpha_1 \cdot f(x_1) + \alpha_2 \cdot f(x_2) + \alpha_3 \cdot f(x_3)) \cdot \frac{\Delta x}{2}$ $\alpha_1 = \alpha_3 = 5/9 \approx 0.556$ $\alpha_2 = 8/9 \approx 0.889$ $\xi_1 = \sqrt{3/5} \approx 0.775$ Sth degree polynomial is integrated exactly	S = 0.775 S = 0.775 S = -0.775 S

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Elements with reduced integration

Integration order of isoparametric plane stress elements



$$\underline{\mathsf{K}}_{e} = \int \mathbf{t} \cdot \underline{\mathsf{B}}^{\mathsf{T}} \cdot \underline{\mathsf{D}} \cdot \underline{\mathsf{B}} \, dx \, dy$$

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Isoparametric elements

Admissible geometries of isoparametric elements



The side nodes must always lay in the middle third of the edge line!

01/23

20

Isoparametric elements

Inadmissible element geometries



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Nonconforming Elements

Modeling of structural regions subjected to bending with plane stress elements



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Shape function: Extension of the bilinear shape function by quadratic terms; Elimination of the additional degree of freedom on element plane. The displacement functions at the boundaries of two adjacent elements are not compatible.

Aim: Elements able to represent "bending" appropriately

Nonconforming Elements

Example: Beam – analysed with plane stress elements

Convergence of stresses $\sigma_{x,m}$ [MN/m²] of a beam in bending





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Nonconforming Elements

Example: Plate – analysed with plane stress elements

FE mesh	Conforming elements	Nonconforming elements
2 x 2	1.66	2.28
4 x 4	4.32	4.72
8 x 8	4.22	4.22

Convergence of the stresses $\sigma_{x,m}$ [MN/m²] of a deep beam

Convergence of stresses $\sigma_{x,m}~$ [MN/m²] of a beam in bending



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Nonconforming Elements

Example: Plate – analysed with plane stress elements



8 x 1 elements - 8-node element

Conclusions

- The 4-node plane stress element is not well suited to model structural parts of plates subjected to bending (shear locking).
- Appropriate elements to model bending are
 - nonconforming 4-node elements
 - isoparametric elements with higher shape functions.
 - hybrid elements



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Hybrid Elements

Hybrid Plate Element



The basic assumptions for hybrid elements are shape functions for the stress inside the element and shape functions for the displacements at the element boundaries.

01/23

27

Hybrid Elements



Principles of virtual work

The stress shape functions result in strains inside the element. The displacements corresponding to those strains are "adjusted" at the displacement shape functions at the boundaries by the principle of virtual work. The principle of virtual displacements leads to an element stiffness matrix with displacements as unknowns as in the case of displacement-based elements.

Hybrid Elements

Hybrid plane stress element with rotational degrees of freedom



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Plate and shell structures

Modeling

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Rectangular element for plates in plane stress

Stiffness matrix for the rectangular element for plates in plane stress



with

$$\begin{aligned} k_{11} &= k_{33} = k_{55} = k_{77} \\ k_{22} &= k_{44} = k_{66} = k_{88} \\ k_{12} &= k_{47} = k_{38} = k_{56} \\ k_{13} &= k_{57} \\ k_{14} &= k_{27} = k_{58} = k_{36} \\ k_{15} &= k_{37} \\ k_{16} &= k_{25} = k_{78} = k_{34} \\ k_{17} &= k_{35} \\ k_{18} &= k_{23} = k_{67} = k_{45} \\ k_{24} &= k_{68} \\ k_{26} &= k_{48} \\ k_{28} &= k_{46} \end{aligned}$$

$$= 4 b/a + 2 (1 - \mu) a/b$$

= 4 a/b + 2 (1 - \mu) b/a
= 3/2 (1 + \mu)
= -4 b/a + (1 - \mu) a/b
= -3/2 (1 - 3 \mu)
= -2 b/a - (1 - \mu) a/b
= -3/2 (1 + \mu)
= 2 b/a - 2 (1 - \mu) a/b
= 3/2 (1 - 3 \mu)
= 2 a/b - 2 (1 - \mu) b/a
= -2 a/b - (1 - \mu) b/a
= -4 a/b + (1 - \mu) b/a



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